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P. and A:

$t=1$: design, One can "allocate" control. Action itself is not contractible.

$t=2$: implement (I) or not (S) (stop)

- decision that can only be taken by the principal P.
- not contractible

Design action:

- C (cooperative)
- N (noncooperative)

agent is "good" or "bad." (Principal believes $\Pr[\text{bad}] = \mu$)

◦ can we use the design stage to learn about the agent?

Payoffs

agent is good

stage 1 actions

| | I | S |
|---|----------|---------|
| C | G, g | $0, 0$ |
| N | $G-l, g$ | $-l, 0$ |

principal

◦ P gains G by implementing
loses l if N chosen

◦ A gains g if P chooses I

agent is bad

| | I | S |
|---|-------------|---------|
| C | $-L, b$ | $0, 0$ |
| N | $-L-l, B+b$ | $-l, B$ |

◦ P loses L by implementing
(and l if N chosen)

◦ A gains b if P chooses I
 B by choosing N

◦ $L > l > 0$

◦ $B > b > 0$

Suppose control is contractible: P can commit to giving control of stage 1 to the agent if some message has been sent

◦ optimal contract: (i) P keeps control in stage 1 if A announces "good," and P then chooses C then I

(ii) if A announces "bad," A receives control with prob $\frac{b}{B}$ then chooses N, and P chooses S. Otherwise P chooses C, S.

P's payoff: $(1-\mu)G - \mu \frac{b}{B}d$

Transferable control: P can not commit to giving control of stage 1 to A if she does not find it in her interest.

- here, only unconditional control works. cannot condition control on messages
- control will be transferred in stage 1 if $\mu < \frac{G}{G+b}$

(iff $(1-\mu)G - \mu d > 0$)

• you really learn about the agent by empowering the agent.

• giving control to the agent implies: (Adghon-Zwolski interpretation)

- (i) transfer of formal authority
- (ii) (noncontractible) information needed for real authority.

Dessein:

- P is informed about the right course of action.
- A may be informed
- A is unsure about the congruence between him and P while P knows it.
- Even if P has formal authority, A may be able, w/prob p , to "get his way."
- \exists prob A knows what he prefers

If p sufficiently large, may want to transfer formal authority to A if congruence parameter is high enough, signalling to A that A might want to give P real authority.

Ignorant-World: $N > 3$ potential projects, all very bad except for two: \circ P's pet project (B for P, βb for A)

\circ A's pet project: αB for P
 b for A

$\circ 0 < \alpha, \beta < 1$

\circ assume P knows all payoffs

\circ A knows all payoffs w/ prob $p < 1$.

\circ P can at cost k , make a "recommendation."

at cost K , make an "order."

\circ contract is an allocation of formal authority

\circ for P w/ orders, principal gets $B - K$
agent gets βb

hard authority \rightarrow

soft authority \rightarrow P w/ recommendation, principal gets $(1-p)B + p\alpha B - k$
agent gets $(1-p)\beta b + pb$

P sends nothing, P gets $p\beta B$
A gets pb

\circ p small, P can just recommend

\circ p larger, might want to do orders. (if congruence small)

\circ congruence large \Rightarrow full delegation

\circ P might want to choose hard authority with some probability to prevent agent from investing in P, so that he is a better follower, which is good for P, since P is informed.

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Assume B is a monetary benefit. $\Pr[\text{return}=1]=B$
(or αB).

Giving a share γ of this to the agent makes him
readier to follow recommendations. Now gets

$$Bb + \gamma B > b + \gamma \alpha B$$

output incentives will backfire if there is disagreement
• should go for input incentives