

Repeated Games w/ Perfect Monitoring

Stage game $G = (N, A, u)$

- finite, simultaneous move game

Let $RG(\delta)$ be a multistage game

- Stages $t=0, 1, 2, \dots$ G is played at each t

- $a^t \in A$ played at t

- $U_i = (1-\delta) \sum_{t=0}^{\infty} \delta^t u_i(a^t)$

Notation:

◦ History: $h^t = (a^0, a^1, \dots, a^{t-1})$

◦ Clearly, $h^{t+1} = (h^t, a^t) = (a^0, a^1, \dots, a^{t-1}, a^t)$

◦ Initial history h^0

◦ Outcome path $a = (a^0, a^1, \dots)$

◦ $s = (s_1, \dots, s_n)$ pure strategy profile

◦ $\sigma = (\sigma_1, \dots, \sigma_n)$ mixed strategy profile

◦ $\sigma^t(h^t)$ mixed action profile at h^t according to σ

◦ $\sigma|h^t$ continuation of σ after h^t

◦ $U(\sigma|h^t)$ vector of continuation values from σ at h^t

SDP for static stage game

	C	D
C	5, 5	0, 6
D	6, 0	1, 1

• a strategy profile σ is SPE iff

• $\forall h^t \forall i$

• at t and thereafter, $j \neq i$ plays according to σ

• at $t+1$ and thereafter, $\forall i$, i plays according to σ

Then i does not want to deviate at h^t .

Grim: C iff \nexists D before

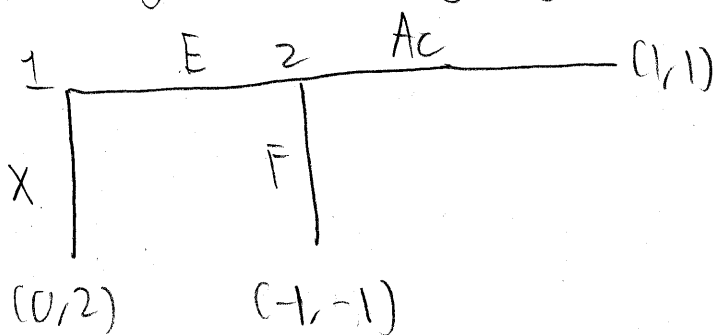
(Grim, Grim) SPE?

• $(C, C, \dots, C) \Rightarrow$ if play C, get $(1-\delta)5 + 5\delta = 5 = V_C$
 if play D, get $(1-\delta)6 + \delta = 6 - 5\delta = V_{D|C}$

• need $V_C \geq V_{D|C} \Leftrightarrow 5 \geq 6 - 5\delta \Leftrightarrow \delta \geq \frac{1}{5}$

• Similarly for if deviate ever occurs

SDP for dynamic stage games



• let a^t be the "path of play of σ " at t
 $a^t \in \{X, EA_c, EF\}$

For $h^t = (a^0, a^1, \dots, a^{t-1})$, define $G(h^t, \sigma) = (N, A, v)$, where $\forall a \in A$,

$$v(a) = (1-\delta)u(a) + \delta U(\sigma | (h^t, a))$$

σ is SPE iff $\forall h^t, \sigma^t(h^t)$ is a SPE of $G(h^t, \sigma)$

Consider:

$$\{E \text{ iff } \exists A_c, A_c \text{ iff } \exists A_c\} = \sigma$$

Suppose $\nexists A_c$ in the past (e.g. $h^t = (x, x, x, EF, x, \dots, x)$)

payoffs: $u_1 = (1-\delta)0 + \delta 0 = 0$ if not enter

$$u_2 = (1-\delta)2 + \delta 2 = 2$$

if EF: $u_1 = (1-\delta)(-1) + \delta 0 = \delta - 1$

$$u_2 = (1-\delta)(-1) + 2\delta = 3\delta - 1$$

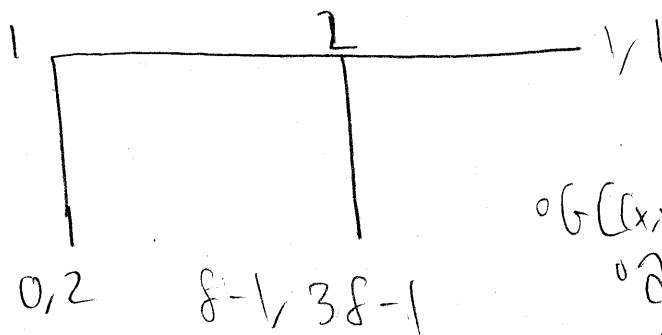
if $\exists A_c$: $u_1 = (1-\delta)1 + \delta 1 = 1$

$$u_2 = (1-\delta)1 + \delta 1 = 1$$

} augmented game

Need $3\delta - 1 \geq 1 \Leftrightarrow \delta \geq \frac{2}{3}$

$0 \geq \delta - 1 \Leftrightarrow \delta \leq 1$



$G((x, x, x, EF, x, \dots, x), \sigma)$

augmented game after h^t, σ .

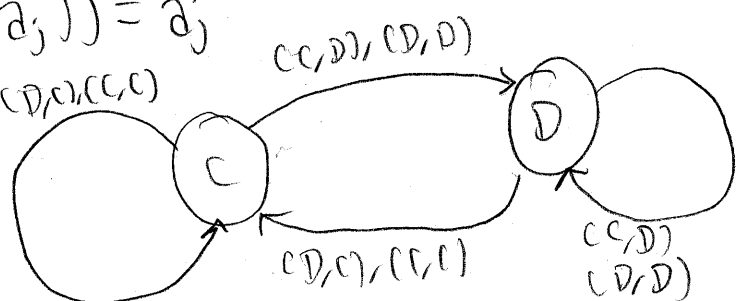
Strategies as automata

An automata for i in $RGC(S)$ consists of:

- a set Q_i of states
- an initial state $q_i^0 \in Q_i$
- an output function $f_i: Q_i \rightarrow \Delta(A_i)$
 - at each state q_i , $f_i(q_i)$ tells you which mixed action to play
- a transition function $\tau_i: Q_i \times A \rightarrow Q_i$

e.g. It-for-it

- C at beginning, afterwards play what other person played
- $Q_i = \{C, D\} = \{\text{what other person did}\}$
- $q_i^0 = C$
- $\tau_i(C) = C, \tau_i(D) = D$
 - $\tau_i(q_i, (a_i, a_j)) = a_j$
- $f_i(q_i) = q_i$



◦ Want to write s_i as an automaton:

◦ $Q_i = \{h^t : t < +\infty\}$

◦ $q_i^0 = h^0$

◦ $\tau_i(q_i, a) = (q_i, a)$

◦ i.e. $q_i = (a^0, \dots, a^{t-1})$

$\tau_i(q_i, a) = (a^0, \dots, a^{t-1}, a)$

◦ $f_i(h^t) = s_i(h^t)$

The strategy σ_i induced by $(Q_i, q_i^0, f_i, \tau_i)$:

◦ $h^0: \sigma_i(h^0) = f_i(q_i^0)$

◦ $h^1 = (a^0): \sigma_i(h^1) = \tau_i(q_i^0, a^0)$

◦ $\sigma_i(h^1) = f_i(q_i^1(h^1))$

◦ $h^2 = (a^0, a^1): \sigma_i(h^2) = \tau_i(q_i^1(a^1), a^1)$

◦ $\sigma_i(h^2) = f_i(q_i^2(h^2))$

◦ $h^t = (a^0, \dots, a^{t-1}): \sigma_i(h^t) = \tau_i(q_i^{t-1}(a^{t-1}), a^{t-1})$

◦ $\sigma_i(h^t) = f_i(q_i^t(h^t))$

a strategy profile σ can be represented

by a grand automaton (Q, q^0, f, τ) where
 $f: Q \rightarrow \prod_{i=1}^n \Delta(A_i)$

◦ e.g. (It-for-tat, It-for-tat)

◦ $Q = A = \{(C, C), (C, D), (D, C), (D, D)\}$

◦ $q^0 = (C, C)$

◦ $\tau(q, (a_1, a_2)) = (a_2, a_1)$

◦ $f(q) = q$

q is accessible from q^0 if $\exists h^+$ with
 $q^+(h^+) = q$

SDP for automata

◦ Given any (Q, q^0, f, τ) , let $V(q^0)$ be the payoff profile from the strategy profile induced by (Q, q^0, f, τ)

◦ Strat. prof. induced by (Q, q^0, f, τ) is SPE iff
 \forall states q accessible from q^0 , $f(q)$ is a NE of (N, A, v) , where
 $v(a) = (1-\delta)u(a) + \delta V(\tau(q, a))$

$$\circ V(C, C) = (5, 5)$$

$$\circ V(C, D) = \left(\frac{6\delta}{1+\delta}, \frac{6}{1+\delta} \right)$$

$$\circ V(D, C) = \left(\frac{6}{1+\delta}, \frac{6\delta}{1+\delta} \right)$$

$$\circ V(D, D) = (1, 1)$$

For (C, C):

	C	D
C	$(1-\delta)5 + \delta 5 = 5$	$(1-\delta)0 + \delta \left(\frac{6}{1+\delta} \right)$
D	$(1-\delta)6 + \delta \left(\frac{6\delta}{1+\delta} \right)$	$(1-\delta)1 + \delta 1 = 1$

$$\circ V(C, C) = 5 \geq (1-\delta)6 + \frac{\delta^2}{1+\delta} 6 = \frac{6}{1+\delta}$$

For (D, C):

	C	D
C	$(1-\delta)5 + \delta 5 = 5$	
D	$\frac{6}{1+\delta}$	$\frac{6\delta}{1+\delta}$

$$\circ \text{Need } \frac{6}{1+\delta} \geq 5 \Leftrightarrow 5 + 5\delta \leq 6$$

$$5\delta \leq 1$$

$$\delta \leq \frac{1}{5}$$

