

Outline:

Multi-agent

- RPE in standard model
- Help
- Collusion-proof

Office hours: Monday 6pm

$$q_1 = a_1 + \varepsilon_1 + \alpha \varepsilon_2 \quad \text{where} \quad \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \end{bmatrix} \sim N\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}\right)$$

$$q_2 = a_2 + \varepsilon_2 + \alpha \varepsilon_1$$

Recall: $v = \frac{1}{1 + \sigma^2 c \eta}$ in single-agent problem

Contract $w_1(q_1, q_2), w_2(q_1, q_2)$. Principal's problem is:

$$\max E[q_1 + q_2 - w_1(q_1, q_2) - w_2(q_1, q_2) \mid a_1, a_2]$$

- ie principal is risk-neutral.

Agents' preferences

$$\circ E[-\exp\{-\mathcal{N}(w_i(q_1, q_2) - \frac{1}{2}c a_i^2)\} \mid a_1, a_2]$$

Consider linear contracts:

$$\circ w_1(q_1, q_2) = z_1 + v_1 q_1 + u_1 q_2$$

$$\circ w_2(q_1, q_2) = z_2 + v_2 q_2 + u_2 q_1$$

Recall: Certainty equivalent

$$E[-\exp\{-\eta[w_i(q_1, q_2) - \frac{1}{2}c a_i^2]\} | a_1, a_2]$$

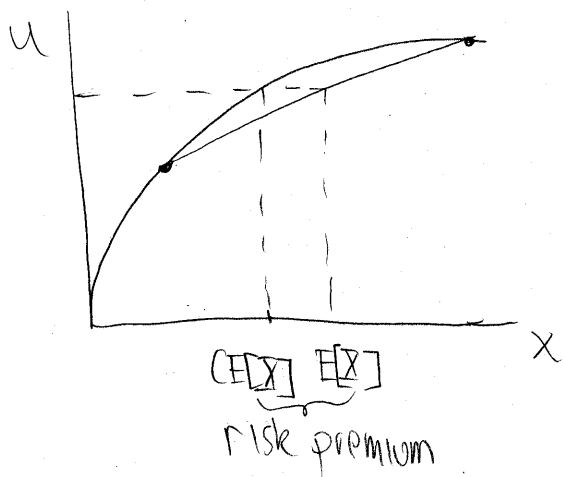
$$= -\exp\{-\eta(z_i + v_i a_i + u_i a_2 - \frac{1}{2}c a_i^2) + \frac{\eta^2}{2}[(v_i + \alpha u_i)^2 \sigma_1^2 + (u_i + \alpha v_i)^2 \sigma_2^2]\}$$

If $\sigma_1^2 = \sigma_2^2 = \sigma^2$, then, this value becomes

$$-\exp\{-\eta(z_i + v_i a_i + u_i a_2 - \frac{1}{2}c a_i^2) + \frac{\eta^2 \sigma^2}{2}[(v_i + \alpha u_i)^2 + (u_i + \alpha v_i)^2]\}$$

Both players want to maximize the certainty equivalent, taking the other player's action as given:

$$\max_{a_i} z_i + v_i a_i + u_i a_i - \frac{1}{2}c a_i^2 - \frac{\eta \sigma^2}{2}[(v_i + \alpha u_i)^2 + (u_i + \alpha v_i)^2]$$



The unique NE is: $a_i^* = \frac{v_i}{c}$

Optimal SB contract solves:

$$\max_{a_i, w_i(c)} E[q_1 + q_2 - w_1(q_1, q_2) - w_2(q_1, q_2)]$$

$$\text{s.t. } CE_1 \geq 0$$

$$CE_2 \geq 0$$

$$a_1 = \frac{v_1}{c}$$

$$a_2 = \frac{v_2}{c}$$

By symmetry, we want to:

$$\max_{a_1, u_1, v_1, z_1} a_1 - [z_1 + v_1 a_1 + u_1 a_2]$$

$$\text{s.t. } 0 = z_1 + v_1 a_1 + u_1 a_2 - \frac{1}{2} c a_1^2 - \frac{m\sigma^2}{2} [(v_1 + \alpha u_1)^2 + (u_1 + \alpha v_1)^2]$$

$$a_1 = \frac{v_1}{c}$$

Can write this:

$$\max_{a, w(c)} CE_p + CE_1 + CE_2$$

$$\text{s.t. } CE_1 \geq 0$$

$$CE_2 \geq 0$$

a solves IC constraints.

Two steps:

1] For a given v_i , use u_i to minimize the variance

2] Choose optimal v_1

Step 1: $(u_1): 2(v_1 + \alpha u_1) \alpha + 2(u_1 + \alpha v_1) = 0$

$$\Rightarrow u_1 = -\frac{2\alpha}{1+\alpha^2} v_1$$

- If $\alpha > 0 \Rightarrow$ penalize if other agent produces more, since own output is more likely to have resulted from positive common shock.

Step 2: Taking FOCs wrt v_1 after substituting the result from step 1 gives

$$v_1 = \frac{1+\alpha^2}{1+\alpha^2 + \eta(\alpha^2(1-\alpha^2))^2}$$

- use more information to reduce variance

- If $\alpha=1$, this is a common shock that we can filter out, giving us:

- $v_1 = 1$

- $u_1 = -1$

Suppose agent 1 can "help" agent 2:

- $q_1 = a^A + \epsilon_1$

- $q_2 = a_2^B + \psi a_2^A + \epsilon_2$

- $C(a_1^A, a_2^A)$ - cost of effort for agent A is convex

Assume $\varepsilon_1, \varepsilon_2$ are iid.

◦ No common shocks $\Rightarrow u_B = 0$

◦ $W_B(q_1, q_2) = z_B + v_B q_2 + u_B q_1$

◦ Do we want $u_A \neq 0$?

◦ Depends on C_{12} , ψ , and risk premium.

Suppose $C(a_1, a_2) = c_1 \frac{a_1^2}{2} + c_2 \frac{a_2^2}{2} + c_{12} a_1 a_2$

Alternatively, think about $C(a_1^A, a_2^A) = (a_1^A + a_2^A)^2$ and $\psi = 1$. Then must have $u_A = v_A$.

◦ Must have $a_1^A + a_2^A = v_A = u_A$

The risk premium must be paid for each task that incentives are provided for, regardless of the effort level chosen.

◦ Don't necessarily want to induce effort on both tasks.

Full side-contracting

3 cases:

$$T^1 = T(q_1, q_2)$$

$$T^2 = T(a_1, a_2)$$

$$T^3 = T(a_1, a_2, q_1, q_2)$$

$$\max \lambda \quad s_1 a_1 + s_2 a_2 - c(a_1) - \frac{n}{2} \sigma^2 [s_1^2 + s_2^2]$$

$$\text{s.t.} \quad (1-s_1)a_1 + (1-s_2)a_2 - c(a_2)$$

$$- \frac{n}{2} \sigma^2 [(1-s_1)^2 + (1-s_2)^2] \geq \text{something}$$

$$\text{since} \quad w_1 + w_2 = v_1 q_1 + u_1 q_2 + v_2 q_2 + u_2 q_1 + z_1 + z_2$$

$$= (v_1 + u_2)q_1 + (v_2 + u_1)q_2 + z_1 + z_2$$

Thus, we need $v_1 + u_2 = v_2 + u_1 = 1$.

We want to minimize the sum of the two risk premiums, in some sense. (We actually want to minimize the harmonic mean of the risk premiums:

$$\text{HM}(x, y) = \frac{1}{\frac{1}{x} + \frac{1}{y}}$$

harmonic mean

• It is like contracting with one agent