

Multi-Tasking

2 dimensions

$$q_1 = a_1 + \varepsilon_1 \quad \varepsilon_1 \sim N(0, \sigma_1^2)$$

$$q_2 = a_2 + \varepsilon_2 \quad \varepsilon_2 \sim N(0, \sigma_2^2)$$

Risk-neutral principal

$$\circ E[q_1 + q_2 - w(q_1, q_2) \mid a_1, a_2]$$

CARA agent with monetary cost:

$$\circ c(a_1, a_2) = \frac{c_1}{2} a_1^2 + \frac{c_2}{2} a_2^2 + c_{12} a_1 a_2$$

$$\circ c_{12}(a_1, a_2) = c_{12} \in \left[0, \sqrt{c_1 c_2} \right]$$

 a_1, a_2 perfect complements

 a_1, a_2 perfect substitutes

$$\circ \bar{u} = -\exp\{-\eta(0)\} = -1$$

Linear contracts

$$\circ w(q_1, q_2) = t + s_1 q_1 + s_2 q_2$$

$$E[-\exp(-\eta X)] \quad , \quad X \sim N(\mu, \sigma^2)$$

$$= -\exp\{-\eta(\mu + \eta \frac{\sigma^2}{2})\} \geq -\exp\{-\eta(0)\}$$

$$\Leftrightarrow \mu + \eta \frac{\sigma^2}{2} \geq 0$$

$$E[-\exp\{-\eta(w(q_1, q_2) - c(a_1, a_2))\}] \geq \bar{u}$$

$$\Rightarrow \underbrace{t + s_1 a_1 + s_2 a_2}_{\text{expected wage}} - \underbrace{\frac{\eta}{2} [s_1^2 \sigma_1^2 + s_2^2 \sigma_2^2]}_{\text{risk premium}} - \underbrace{\left[\frac{c_1}{2} a_1^2 + \frac{c_2}{2} a_2^2 + c_{12} a_1 a_2 \right]}_{\text{cost of effort}} \geq \bar{u} \quad (\text{IR})$$

Want to:

$$\max (1-s_1)a_1 + (1-s_2)a_2 - t$$

$$\text{s.t. } t + s_1 a_1 + s_2 a_2 - \frac{\eta}{2} [s_1^2 \sigma_1^2 + s_2^2 \sigma_2^2]$$

$$- \left[\frac{c_1}{2} a_1^2 + \frac{c_2}{2} a_2^2 + c_{12} a_1 a_2 \right] \geq 0 \quad (\text{ICR})$$

$$(a_1): s_1 - c_1 a_1 - c_{12} a_2 = 0$$

$$(\text{IC} - a_1)$$

$$(a_2): s_2 - c_2 a_2 - c_{12} a_1 = 0$$

$$(\text{IC} - a_2)$$

$$\Rightarrow a_2 = \frac{s_2 - c_{12} a_1}{c_2}$$

$$\Rightarrow s_1 - c_1 a_1 - c_{12} \frac{s_2 - c_{12} a_1}{c_2} = 0$$

$$\Rightarrow a_1 = \frac{s_1 c_2 - s_2 c_{12}}{c_1 c_2 - c_{12}^2}$$

$$a_2 = \frac{s_2 c_1 - s_1 c_{12}}{c_1 c_2 - c_{12}^2}$$

$\max_{s_1, s_2} \Omega(s_1, s_2 | \alpha)$, let $(s_1^*(\alpha), s_2^*(\alpha)) \in \arg \max_{s_1, s_2} \Omega(s_1, s_2 | \alpha)$.

Thm: If $\bullet \frac{\partial^2 \Omega}{\partial s_1 \partial s_2} \geq 0$ $\bullet \frac{\partial^2 \Omega}{\partial s_2 \partial \alpha_i} \geq 0$, then

$\bullet \frac{\partial^2 \Omega}{\partial s_1 \partial \alpha_i} \geq 0$

$$\frac{\partial s_1^*}{\partial \alpha_i} \geq 0, \quad \frac{\partial s_2^*}{\partial \alpha_i} \geq 0$$

Substituting in the IR constraint into the objective function:

$$\max_{s_1, s_2} d_1 + d_2 - \frac{\mu}{2} [s_1^2 \sigma_1^2 + s_2^2 \sigma_2^2] - \left[\frac{c_1}{2} d_1^2 + \frac{c_2}{2} d_2^2 + c_{12} d_1 d_2 \right]$$

$$\text{s.t. } d_1 = \frac{s_1 c_2 - s_2 c_{12}}{c_1 c_2 - c_{12}^2}$$

$$d_2 = \frac{s_2 c_2 - s_1 c_{12}}{c_1 c_2 - c_{12}^2}$$

$$\bullet \text{sign} \left(\frac{\partial^2 \Omega}{\partial s_1 \partial s_2} \right) = \text{sign}(c_{12}) \geq 0$$

$$\bullet \text{sign} \left(\frac{\partial^2 \Omega}{\partial s_1 \partial (-\sigma_1^2)} \right) = \text{sign}(\mu s_1 \sigma_1^2) \geq 0$$

$$\bullet \text{sign} \left(\frac{\partial^2 \Omega}{\partial s_2 \partial (-\sigma_1^2)} \right) = \text{sign}(0) = 0$$

Result:

◦ If $\sigma_1^2 \uparrow \Rightarrow s_1 \downarrow$

◦ If $\sigma_1^2 \uparrow \Rightarrow s_2 \downarrow$ by supermodularity

$$\frac{\partial s_1^*}{\partial (-\sigma_1^2)} \geq 0 \Leftrightarrow \frac{\partial s_1^*}{\partial \sigma_1^2} \leq 0$$

$$\frac{\partial s_2^*}{\partial (-\sigma_1^2)} \geq 0 \Leftrightarrow \frac{\partial s_2^*}{\partial \sigma_1^2} \leq 0$$

Task Exclusion

◦ Principal cares about q_1

◦ agent cares about q_2

◦ might want to exclude a certain task

Job Design

◦ $q_i = a_i + \varepsilon_i$, $\varepsilon_i \sim N(0, \sigma_i^2)$

and $c(a_1, a_2) = (a_1 + a_2)^2$

◦ want to group tasks that are "measurable"
(i.e. σ_i^2 small)

Can show that there is a cut-off σ_2^* s.t.

$\sigma_i^2 < \sigma_2^* \Rightarrow$ put both tasks together

$\sigma_i^2 > \sigma_2^* \Rightarrow$ put this task with other agent.

Advocates and Conflicts

Suppose

$$q_1 = a_1 - \gamma a_2 + \varepsilon_1$$

$$q_2 = a_2 - \gamma a_1 + \varepsilon_2$$

• Do we want these tasks to be grouped?

Baker: No uncertainty. Misalignment of incentives

$$V(a_1, a_2) = v_1 a_1 + v_2 a_2$$

• can only observe $P(a_1, a_2) = p_1 a_1 + p_2 a_2$

• can only contract on P :

• e.g. $t + sP$. How do we find s ?

Can show that

$$s = \frac{v_1 f_1 + v_2 f_2}{f_1^2 + f_2^2} = \frac{\|v\| \|f\| \cos(\gamma)}{\|f\|^2}$$

Next problem set due in a week