

1] Intro

$$y_t = \underbrace{g(w_t)} + \varepsilon_t \quad \text{where } E[\varepsilon_t | w_t] = 0$$

$$E[y_t | w_t]$$

° Conditional expectation function

Three topics:

$$1] g(w_t) \approx \underbrace{\bar{X}_t' \beta}_{=f(w_t)}$$

2] Estimate β

3] Make inference on $\bar{X}_t' \beta$.

OLS in population

First, we will begin with some basic properties of the conditional expectation function.

° The CEF is the best predictor of y_t given w_t . That is, $g(w) = \underset{\tilde{g} \in \mathbb{R}}{\operatorname{argmin}} E[(y_t - \tilde{g})^2 | w]$

° To see this, take FOCs:

$$(\tilde{g}): 2E[(y - \tilde{g}) | w] = 0$$

$g(w) = E[y | w]$ satisfies this.

What is $\underset{\tilde{g} \in G}{\operatorname{argmin}} E[(y - \tilde{g}(w))^2]$?
 $\tilde{g} \in G$
set of measurable functions

° It turns out $g(w) = E[y | w] = \underset{\tilde{g} \in G}{\operatorname{argmin}} E[(y - \tilde{g}(w))^2]$

° Follows by the law of iterated expectations.

$$\begin{aligned} \text{since } E[(y - \hat{g}(w))^2] &= E[E[(y - g(w))^2 | w]] \\ &\stackrel{\Delta}{=} E[\min_{\hat{g} \in \mathbb{R}} E[(y - \hat{g})^2 | w]] \end{aligned}$$

Basic properties of OLS:

$$\beta = \underset{b \in \mathbb{R}^k}{\operatorname{argmin}} Q(b), \text{ where } Q(b) = E[(y_t - x_t' b)^2]$$

◦ in population

◦ $x_t' \beta$ is the best linear predictor of y_t with respect to mean squared error.

In finite samples,

$$\begin{aligned} \hat{\beta} &= \underset{b \in \mathbb{R}^k}{\operatorname{argmin}} Q_n(b), \text{ where } Q_n(b) = \frac{1}{n} \sum_{t=1}^n (y_t - x_t' b)^2 \\ &= E_n[(y_t - x_t' b)^2] \end{aligned}$$

◦ remark: E_n is a short-hand for $\frac{1}{n} \sum_{t=1}^n$

◦ in finite samples, $x_t' \hat{\beta}$ is the best linear predictor of y_t .

Explicit solutions:

The FOCs for $\min_{b \in \mathbb{R}^k} Q(b)$ are given by:

$$(b): E[(y_t - x_t' \beta) x_t] = 0 \Rightarrow E[x_t y_t - x_t x_t' \beta] = 0$$

$$\Rightarrow E[x_t x_t'] \beta = E[x_t y_t]$$

$$\Rightarrow \beta = \left\{ \underbrace{E[x_t x_t']}_{k \times k} \right\}^{-1} \underbrace{E[x_t y_t]}_{k \times 1}$$

assume $E[x_t x_t']$ is nonsingular

$$\Rightarrow \beta = [\text{Var}(x_t)]^{-1} \text{Cov}(x_t, y_t)$$

FOCs for $\min_{b \in \mathbb{R}^k} Q_n(b)$ are:

$$Q_n(b): E_n[x_t(y_t - x_t' \hat{\beta})] = 0$$

assuming $E_n[x_t x_t']$ is nonsingular

$$\Leftrightarrow \hat{\beta} = [E_n[x_t x_t']]^{-1} E_n[x_t y_t]$$

$$= \left[\frac{1}{n} \sum_{t=1}^n x_t x_t' \right]^{-1} \frac{1}{n} \sum_{t=1}^n x_t y_t$$

$$= (X'X)^{-1} X'Y, \text{ where } X = \begin{bmatrix} x_1' \\ \vdots \\ x_n' \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

OLS is the best linear approximation to
 $g(w) = E[y|w]$. (BLA property)

• i.e. $\beta = \underset{b \in \mathbb{R}^k}{\text{argmin}} E \left[\underbrace{(g(w_t) - x_t' b)^2}_{\text{specification error}} \right]$ given $x_t = f(w_t)$

• that is, β minimizes the expected specification error.

• To show this, note that $y_t = E[y_t | w_t] + \varepsilon_t, E[\varepsilon_t | w_t] = 0$

$$Q(b) = E[(y_t - x_t' b)^2] = E\left[\left(E[y_t | w_t] - x_t' \beta + \varepsilon_t \right)^2 \right]$$

$$= E\left[\left(E[y_t | w_t] - x_t' b \right)^2 \right] + E[\varepsilon_t^2]$$

$$+ 2 E\left[\left(E[y_t | w_t] - x_t' b \right) \varepsilon_t \right]$$

$$= E\left[\left(E[y_t | w_t] - x_t' b \right)^2 \right] + E[\varepsilon_t^2]$$

= 0 by law of iterated expectations

$$= E\left[(g(w_t) - x_t' b)^2 \right] + E[\varepsilon_t^2]$$

$$\begin{aligned}\text{Thus, } \beta &= \underset{b \in \mathbb{R}^k}{\operatorname{argmin}} Q(b) = \underset{b \in \mathbb{R}^k}{\operatorname{argmin}} \{E[(g(w_t) - x_t' b)^2] + E[\varepsilon_t^2]\} \\ &= \underset{b \in \mathbb{R}^k}{\operatorname{argmin}} E[(g(w_t) - x_t' b)^2]\end{aligned}$$

Remark:

$$\begin{aligned}E[(E[y_t | w_t] - x_t' b) \varepsilon_t] &= E[E[(E[y_t | w_t] - x_t' b) \varepsilon_t | w_t]] \\ &= E[(E[y_t | w_t] - x_t' b) \underbrace{E[\varepsilon_t | w_t]}_{=0}] = 0\end{aligned}$$

Buy Judd's Numerical Methods in Economics.