

$f(x; \theta)$  parametric estimation

a) Method of moments

$$\mu_i' = \int x^i f_X(x, \theta) dx = \mu_i'(\theta)$$

• approximate (sample analog) the sample moment

$$\mu_1 = \mu_1(\theta) \quad \bar{X} \xrightarrow{P} \mu$$

$$\mu_2' = \mu_2'(\theta) \quad \frac{1}{n} \sum_{i=1}^n \bar{X}_i^2 \xrightarrow{P} \mu_2'$$

$$\left. \begin{aligned} \text{Let } \mu_1(\hat{\theta}) &= \bar{X} \\ \mu_2'(\hat{\theta}) &= \frac{1}{n} \sum_{i=1}^n \bar{X}_i^2 \end{aligned} \right\} \text{ solve for } \hat{\theta}$$

Example 7.2.1

$$\bar{X}_i \stackrel{iid}{\sim} N(\mu, \sigma^2)$$

$$\bullet \hat{\mu} = \bar{X}$$

$$\bullet \hat{\mu}_2' = \frac{1}{n} \sum_{i=1}^n \bar{X}_i^2$$

$$\Rightarrow \hat{\sigma}^2 = \hat{\mu}_2' - (\hat{\mu})^2 = \frac{1}{n} \sum_{i=1}^n \bar{X}_i^2 - \left( \frac{1}{n} \sum_{i=1}^n \bar{X}_i \right)^2$$

$$= \frac{1}{n} \sum_{i=1}^n (\bar{X}_i - \bar{X})^2 = \bar{S}^2$$

Remarks:

1] Robust and constructive

2] Estimators are functions of sums of rvs.

3] Results may be non-sensible

e.g. 7.2.2.

Let  $X_i \stackrel{iid}{\sim}$  Binomial  $(k, p)$

$$E[X_i] = kp \Rightarrow \hat{k}\hat{p} = \bar{X}$$

$$\text{Var}(X_i) = kp(1-p) \Rightarrow E[X_i^2] = kp(1-p) + k^2 p^2$$

$$\Rightarrow \frac{1}{n} \sum_{i=1}^n X_i^2 = \hat{k}\hat{p}(1-\hat{p}) + \hat{k}^2 \hat{p}^2$$

$$\Rightarrow \hat{p} = \frac{\bar{X}}{\hat{k}}$$

$$\hat{k} = \frac{\bar{X}^2}{\bar{X} - \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X})^2}$$

but  $\hat{k}$  can be negative!

• MM is ignoring information here.

4] Many possible moments for most problems.  
(ie can use covariances.)

5] Getting "enough" moments is rarely the problem

6] Repopularized in economics (Hansen, EMA '82)  
• GMM

### Maximum Likelihood

Defn 6.3.1 Let  $f(x|\theta)$  be the joint pdf of the sample  $X = (X_1, \dots, X_n)$ . Given that  $\bar{X} = x$  is observed, the function of  $\theta$  given by  $L(\theta|x) = f(x|\theta)$  is called the likelihood function.

e.g.  $\text{Bin}(n, p)$

$$L(p | n, x) = \binom{n}{x} p^x (1-p)^{n-x}$$

Defn 7.2.4: For each sample point  $x$ , let  $\hat{\theta}(x)$  be the parameter at which  $L(\theta | x)$  achieves a maximum. A maximum likelihood estimator (MLE) of  $\theta$  is  $\hat{\theta}(x)$

e.g.  $X_1, \dots, X_n \sim \text{Bernoulli}(p)$

$$L(p | x) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i}$$

$$= p^{\sum_{i=1}^n x_i} (1-p)^{n - \sum_{i=1}^n x_i} = p^{\bar{Y}} (1-p)^{n-\bar{Y}}$$

Taking first order conditions of  $\log L = \bar{Y} \log p + (n-\bar{Y}) \log(1-p)$

$$(p): \frac{\bar{Y}}{p} = \frac{n-\bar{Y}}{1-p} \Rightarrow \bar{Y} - p\bar{Y} = np - p\bar{Y}$$

$$\Rightarrow p = \frac{1}{n} \bar{Y} = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}$$

Remarks:

1] Maximization is over the "parameter space":  $\theta \in \Theta$

(e.g.  $p \in [0, 1]$ )

• can't get any "stupid" answers

2] Order preserving transforms

① Independence:  $\prod_{i=1}^n f_i(x_i | \theta) \stackrel{\text{logs}}{\Rightarrow} \sum_{i=1}^n \log(f_i(x_i | \theta))$

② Many densities (esp. exponential family) have  $e^{(\cdot)}$ .  
Taking logs helps!

③ Main problem: ensuring maximum.

① Second-order conditions

② Local maximums

③ If  $\Theta$  is bdd, watch out for boundary conditions

④ Multiple solutions. (identification)

④ "Pretend" normality  $\Rightarrow$  MLE

◦ Quasi-MLEs (QMLE)

⑤ First order condition as function of  $\theta$  from log-likelihood is the "score"

$$s(\theta|x) = \frac{\partial}{\partial \theta} \log L(\theta|x)$$

◦ Clearly,  $s(\hat{\theta}|x) = \frac{\partial}{\partial \theta} \log L(\hat{\theta}|x) = 0$  if  $\hat{\theta}$  is MLE.

⑥ Invariance properties.

◦ If  $\hat{\theta}(x)$  is MLE of  $\theta$ . Let  $T$  be a fn of  $\theta$ . Then  $T(\hat{\theta}) = T(\hat{\theta}(x))$

## Bayes Estimators

$L(\theta|x)$

$\pi(\theta)$  density for  $\theta$  reflecting uncertainty over  $\theta$   
◦ the "prior"

•  $\pi(\theta)$  is what I thought  $\theta$  might look like before I saw the data. What do I think after I see  $x$ ?

$$L(X, \theta) = \pi(\theta | x) \cdot \overset{\downarrow \text{marginal of } X}{m(x)}$$

$$= f(X | \theta) \cdot \pi(\theta)$$

$$\Rightarrow f(X | \theta) \cdot \pi(\theta) = \pi(\theta | X) m(X)$$

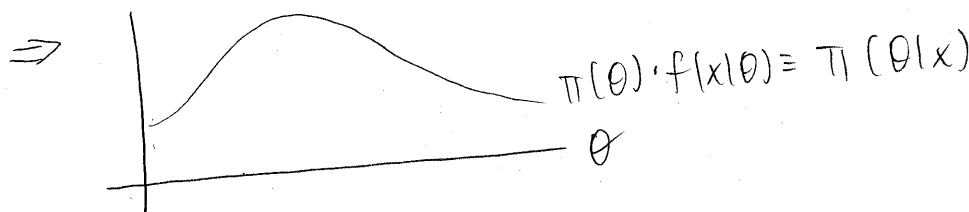
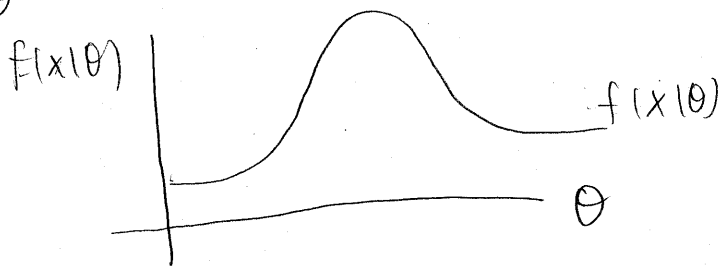
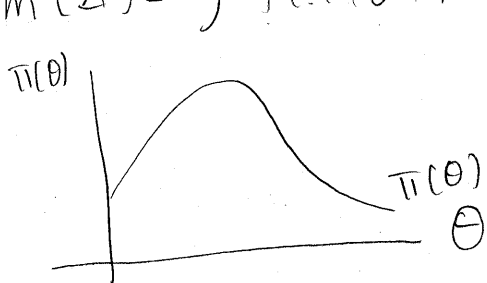
$$\Rightarrow \pi(\theta | X) = \frac{f(X | \theta) \pi(\theta)}{m(X)}$$

"Bayes' rule"

posterior density for  $\theta$

$\frac{m(X)}{m(X)}$  ensures we have a density (scales up/down)

$$m(X) = \int f(x | \theta) \pi(\theta) d\theta$$



e.g 7.2.14  $X_i \sim \text{Bernoulli}$   $\bar{X} = \sum_{i=1}^n X_i \sim \text{Bin}(n, p)$

Suppose  $\pi(p) \sim \text{Beta}(\alpha, \beta)$

$$m_{\bar{X}}(y) = \int f(y | p) \pi(p) dp$$

$$f(y | p) = \binom{n}{y} p^y (1-p)^{n-y}$$

$$\pi(p) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha) \Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1}$$

$$\Rightarrow m_{\bar{Y}}(y) = \binom{n}{y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \frac{\Gamma(y+\alpha)\Gamma(n-y+\beta)}{\Gamma(n+\alpha+\beta)}$$

$$\Rightarrow \pi(p|y) = \frac{f(y|p)\pi(p)}{m_{\bar{Y}}(y)} \sim \text{Beta}(y+\alpha, n-y+\beta)$$

$$E[\pi(p|y)] = \frac{y+\alpha}{y+\alpha+n-y+\beta} = \frac{y+\alpha}{\alpha+\beta+n} = \left(\frac{n}{\alpha+\beta+n}\right)\left(\frac{y}{n}\right) + \left(\frac{\alpha+\beta}{\alpha+\beta+n}\right)\left(\frac{\alpha}{\alpha+\beta}\right)$$

◦ weighted average of sample mean and prior mean.

◦ "A Bayesian is a person who expects to see a horse, sees a donkey, and concludes it's a mule."

### Remarks:

1] Precise mathematical formulation to "what do I learn when I observe  $X=x$ ?"

2] Results depend on prior.

3] where does  $\pi(\theta)$  come from?

- mathematical tractability (conjugate priors)
- conjugate of normal is normal
- conjugate of binomial is beta

4] Improper priors:  $\int \pi(\theta) d(\theta) \neq 1$

- e.g.  $\pi(\theta|x) \propto f(x|\theta)\pi(\theta)$   
is proportional to

• can force it to integrate to one.  
5] often, certain priors lead to classical results (MLEs)

Next time: Evaluating these estimators.