

Indivisible public project

◦ value s for consumers

◦ cost: $c = \beta - \frac{e}{\text{efficiency parameter}}$

◦ Find cheapest contract which allows project to be implemented

◦ utility of firm: $\overbrace{u}^{\text{profits}} = \underbrace{t}_{\text{transfer from govt}} - \underbrace{\psi(e)}_{\text{cost of effort}}$ $\psi' > 0$
 $\psi'' > 0$

◦ λ shadow cost of public funds

◦ consumers' payoff is: $s - (1 + \lambda)(\underbrace{t + \beta - e}_{\text{cost}})$

◦ utilitarian regulator: $W = s - (1 + \lambda)(t + \beta - e) + t - \psi(e)$
 $= s - (1 + \lambda)(\beta - e + \psi(e)) - \lambda u$

Complete information:

◦ regulator: $\max_e s - (1 + \lambda)(\beta - e + \psi(e)) - \lambda u$
s.t. $u \geq 0$

(e): $\psi'(e^*) = 1$
efficient effort

and $t^* = \psi(e^*)$
firm breaks even (no rents)

Asymmetric information: assume $\beta \sim F(\beta)$ on $[\underline{\beta}, \bar{\beta}]$

◦ regulator: $\max_{e(\beta), u(\beta)} \int_{\underline{\beta}}^{\bar{\beta}} [s - (1 + \lambda)(\beta - e(\beta) + \psi(e(\beta))) - \lambda u] \frac{dF(\beta)}{f(\beta)d\beta}$

$$\text{s.t. } u(\bar{\beta}) \geq 0$$

(IR)

$$u'(\beta) = -\psi'(e(\beta))$$

(IC)

$$e'(\beta) \leq 1$$

(Monotonicity)

Rewriting the objective function:

$$\max_{e(\beta)} \int_{\underline{\beta}}^{\bar{\beta}} [s - c(1+\lambda)(\beta - e(\beta) + \psi(e(\beta))) - \lambda \frac{F(\beta)}{f(\beta)} \psi'(e(\beta))] dF(\beta)$$

$$(e(\beta)): \psi'(e(\beta)) = 1 - \frac{\lambda}{1+\lambda} \frac{F(\beta)}{f(\beta)} \psi''(e(\beta))$$

Clearly, $\psi'(e(\beta)) = 1 \Rightarrow$ no distortions at the top
since $F(\bar{\beta}) = 0$

Bunching and Ironing:

$$\max_{q(\theta), T(\theta)} \int_{\underline{\theta}}^{\bar{\theta}} [T(\theta) - cq(\theta)] dF(\theta)$$

$$\text{s.t. } \underline{\theta} v(q(\theta)) - T(\theta) \geq 0 \quad (\text{IR})$$

$$T'(\theta) = \theta v'(q(\theta)) \quad \forall \theta \quad (\text{IC})$$

$$\frac{dq(\theta)}{d\theta} \geq 0 \quad \forall \theta \quad \text{monotonicity}$$

Typically, we assume $\frac{dq(\theta)}{d\theta} \geq 0$ and verify that the solution satisfies this.

$$\left[\theta - \frac{1-F(\theta)}{f(\theta)} \right] v'(q(\theta)) = c \Leftrightarrow g(\theta) v'(q(\theta)) = c \quad (*)$$

Does this satisfy $\frac{dq(\theta)}{d\theta}$?

• Sufficient condition: $h(\theta) = \frac{f(\theta)}{1-F(\theta)} \uparrow$ and $v'' < 0$

$$(*) \Rightarrow \frac{dq}{d\theta} = - \frac{\overbrace{g'(\theta) v'(q(\theta))}^{>0}}{\underbrace{v''(q(\theta))}_{<0} \underbrace{g(\theta)}_{>0}} > 0 \quad \text{since } c > 0 \text{ and } v'(q(\theta)) > 0$$

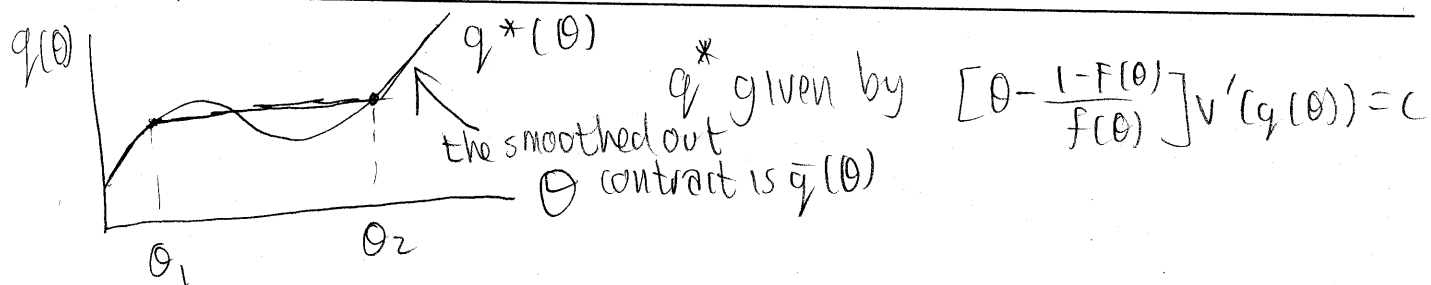
$> 0 \quad \text{iff } g'(\theta) > 0$

$$h'(\theta) = \frac{f'(\theta)(1-F(\theta)) + (f(\theta))^2}{(1-F(\theta))^2}$$

$$g'(\theta) = \frac{f'(\theta)(1-F(\theta)) + 2(f(\theta))^2}{(f(\theta))^2}$$

$$\begin{aligned} h'(\theta) > 0 &\Rightarrow f'(\theta)(1-F(\theta)) + (f(\theta))^2 > 0 \\ &\Rightarrow f'(\theta)(1-F(\theta)) + 2(f(\theta))^2 > 0 \\ &\Rightarrow g'(\theta) > 0 \Rightarrow \frac{dq}{d\theta} > 0 \end{aligned}$$

Noldeke and Samwelson: optimal bonding without optimal control



For some range, $\frac{dq^*(\theta)}{d\theta} < 0$. Need to impose $\frac{dq(\theta)}{d\theta} \geq 0$

$$\max_{q(\theta)} \int_{\underline{\theta}}^{\bar{\theta}} [\theta v(q(\theta)) - cq(\theta) - \frac{v(q(\theta))}{h(\theta)}] dF(\theta)$$

s.t. $\frac{dq(\theta)}{d\theta} \geq 0$

Assume objective function strictly concave in θ .

• $\frac{dq^*(\theta)}{d\theta}$ changes signs only a finite * of times.

$$\max_{q(\theta)} \int_{\underline{\theta}}^{\bar{\theta}} [\theta v(q(\theta)) - cq(\theta) - \frac{v(q(\theta))}{h(\theta)}] dF(\theta)$$

s.t. $\frac{dq(\theta)}{d\theta} = \mu(\theta), \mu(\theta) \geq 0$

The associated Hamiltonian is:

$$H(\theta, q, \mu, \lambda) = [\theta v(q(\theta)) - cq(\theta) - \frac{v(q(\theta))}{h(\theta)}] f(\theta) + \lambda(\theta) \mu(\theta)$$

$$1] H(\theta, \bar{q}(\theta), \bar{\mu}(\theta), \bar{\lambda}(\theta)) \geq H(\theta, \bar{q}(\theta), \mu(\theta), \bar{\lambda}(\theta))$$

$$2] \frac{d\lambda(\theta)}{d\theta} = -\left[\left(\theta - \frac{1}{h(\theta)}\right) v'(\bar{q}(\theta)) - c\right] f(\theta)$$

$$\exists \lambda(\hat{\theta}) = \lambda(\bar{\theta}) = 0 \quad (\text{transversality cond.})$$

$$\forall \mu(\theta) \geq 0$$

Integrating (2):

$$\lambda(\hat{\theta}) = - \int_{\hat{\theta}}^{\bar{\theta}} \left[\left(\theta - \frac{1}{h(\theta)} \right) v'(\bar{q}(\theta)) - c \right] f(\theta) d\theta$$

By transversality,

$$0 = \lambda(\bar{\theta}) = - \int_{\bar{\theta}}^{\bar{\theta}} \left[\left(\theta - \frac{1}{h(\theta)} \right) v'(\bar{q}(\theta)) - c \right] f(\theta) d\theta$$

When $\lambda(\hat{\theta}) \leq 0$, $\mu(\theta) = 0$

$$\text{But } \mu(\theta) = \frac{dq(\theta)}{d\theta}$$

$$\text{Thus, } \frac{d\bar{q}(\hat{\theta})}{d\theta} \int_{\hat{\theta}}^{\bar{\theta}} \left[\left(\theta - \frac{1}{h(\theta)} \right) v'(\bar{q}(\theta)) - c \right] f(\theta) d\theta = 0$$

$$\text{If } \frac{d\bar{q}(\hat{\theta})}{d\theta} > 0, \quad \left[\theta - \frac{1}{h(\theta)} \right] v'(\bar{q}(\theta)) = c$$

$$\Rightarrow \bar{q}(\theta) = q^*(\theta) \quad \text{on the intervals on which} \\ \frac{d\bar{q}(\theta)}{d\theta} > 0$$